

Introduction to Scientific Visualization

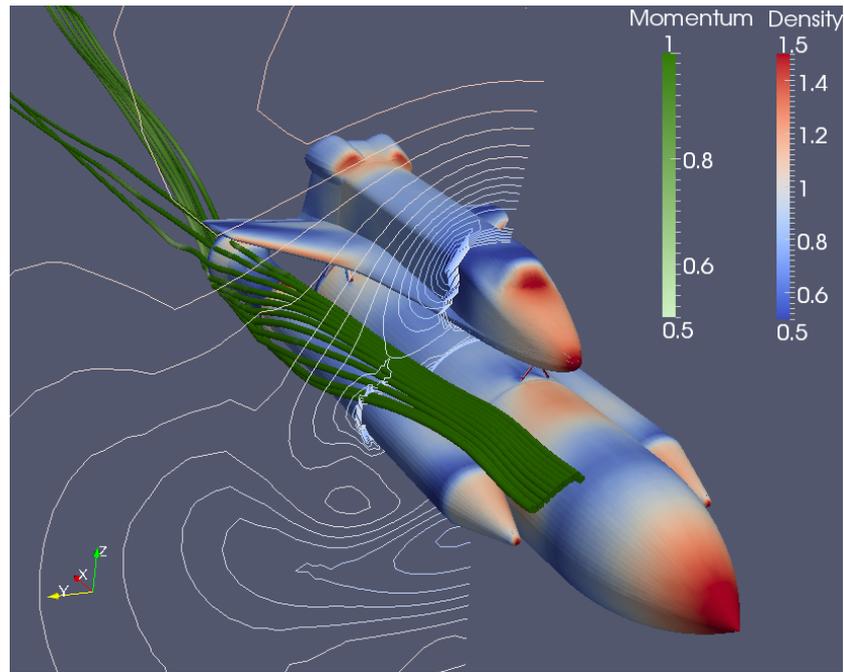
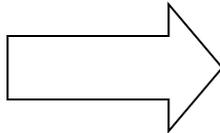
(some slides from Hong Qin)

What is Scientific Visualization

- 1987 the US National Science started “Visualization in scientific computing” as a new discipline,
 - ACM coined the term “scientific visualization”
- Scientific visualization, briefly defined:

*The use of computer graphics
for **analysis and presentation**
of computed or measured scientific data*

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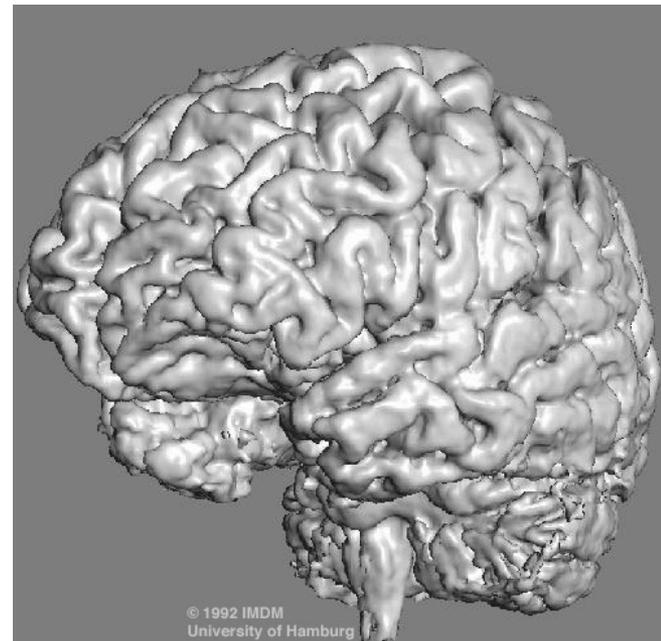
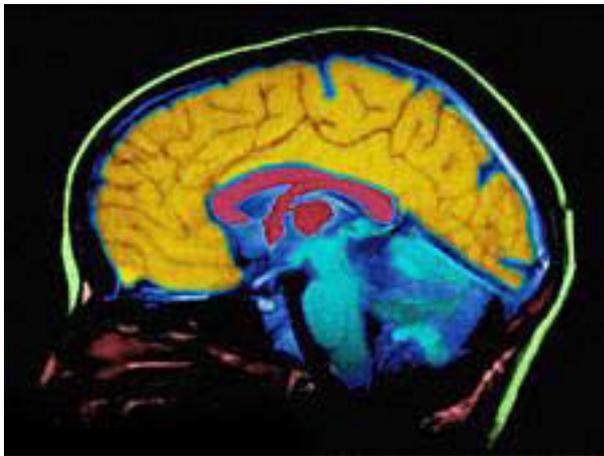
Motivations of Visualization

- Make sense of huge data-sets
- NYSE makes hundreds of millions of transactions per day
- The Large Hadron Collider (LHC) produces 25Gb/sec of data with each experiment
- Uncover insights hidden in the data
- Extract important features and meaningful knowledge of the data to assist in the decision-making process

Examples: Medical

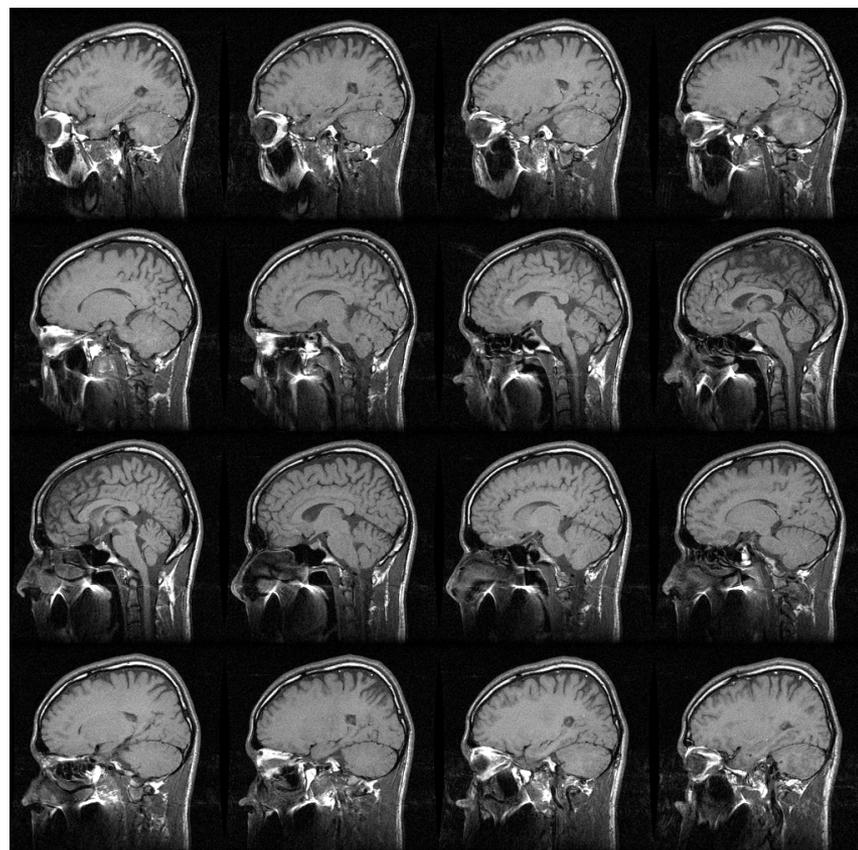
Medical imaging

- X-ray Computed Tomography (CT)
- Magnetic Resonance Imaging (MRI)



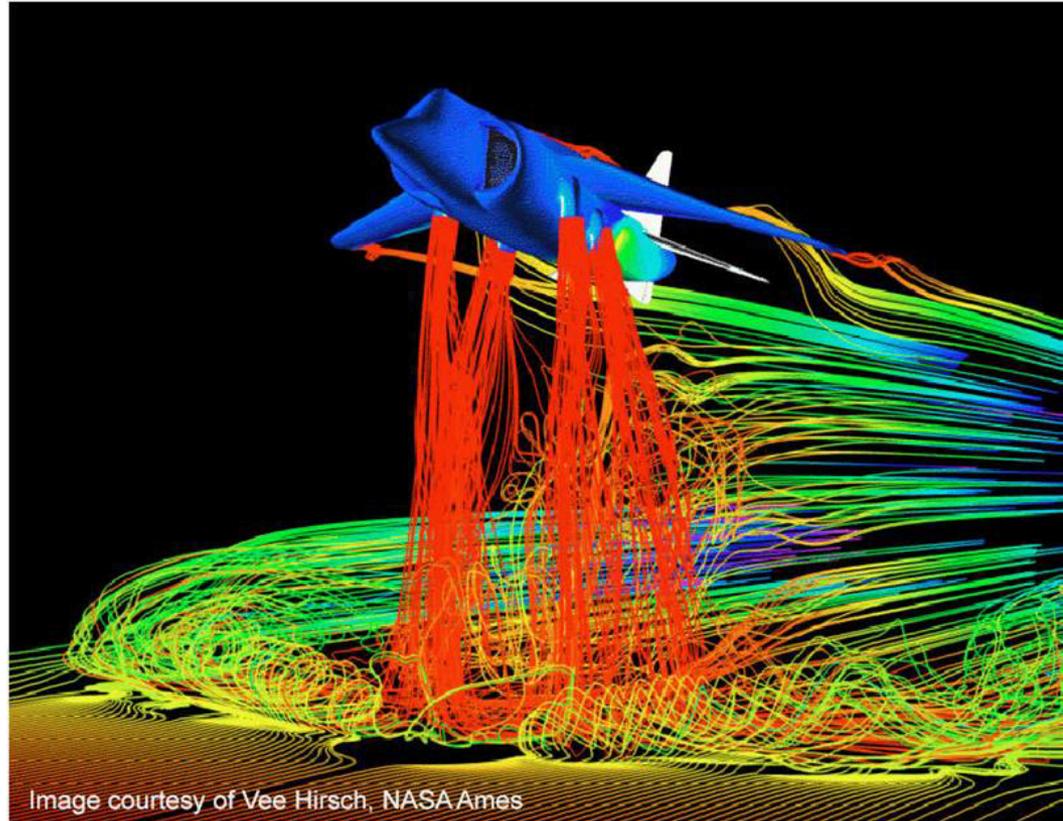
Example Medical

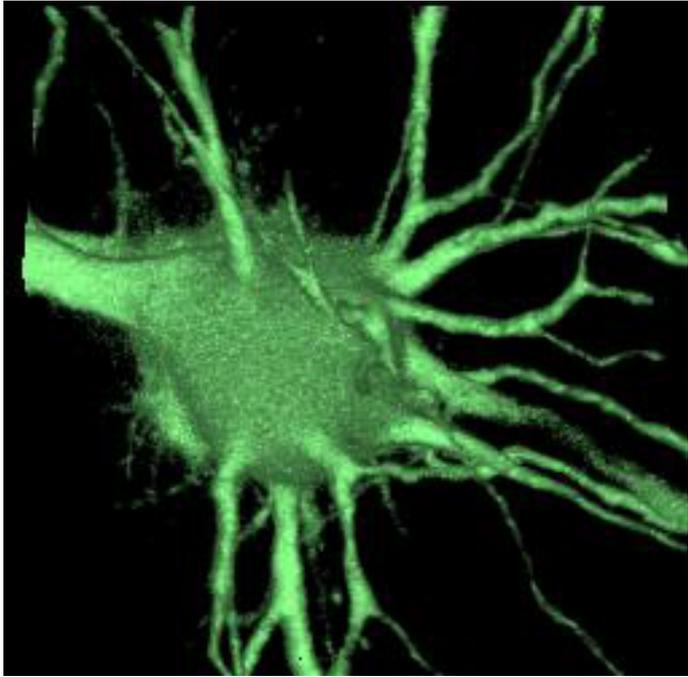
- CT and MRI generate slides
 - Cross-sections of the patient
 - Slices are combined to produce a volumetric representation
- But CT and MRI machines just output numbers – where do the gray values come from?



Example Simulations

- Scientific simulations
- Visualize the results of very sophisticated super-computer simulations
- Computational fluid dynamics example:
 - What quantities are being visualized?





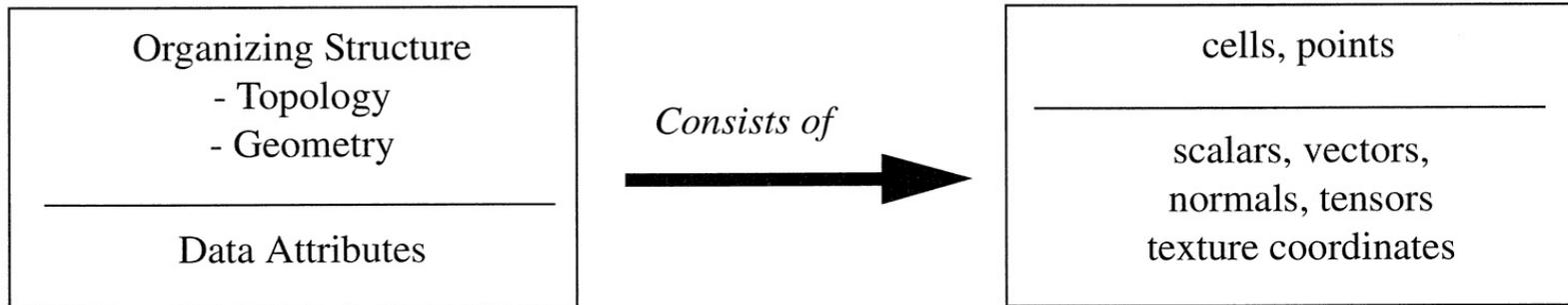
Data

Representations

- Many ways to represent data
- Points (e.g., 3D raster, point cloud)
- Lines
- Vectors
- These are all **discrete** data representations
- Data can be **regular** or **irregular**
- Regular = relationship exists between data points
- Compare: 3D raster vs. point cloud
- Data also has **dimension**: 1, 2, 3, ..., n, ...

Dataset = Structure + Attributes

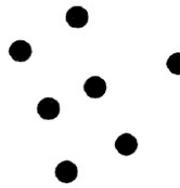
- Structure = topology and geometry
- Topology refers to characteristics unchanged by transformations (holes, handles, branches)
- Geometry refers to (x,y,z) positions of data points



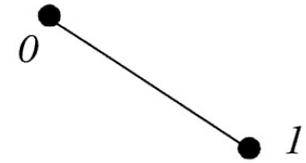
- **cells** define topology, **points** define geometry
- Linear cell types and non-linear cell types



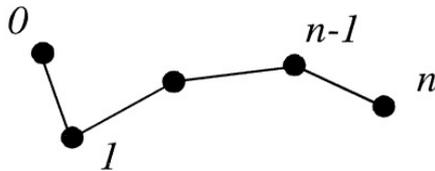
(a) Vertex



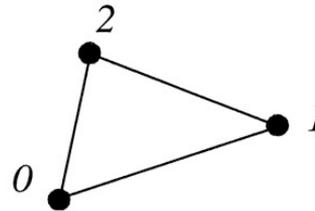
(b) Polyvertex



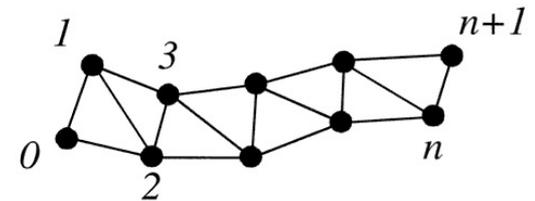
(c) Line



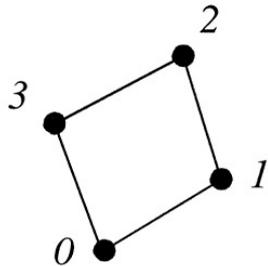
(d) Polyline (n lines)



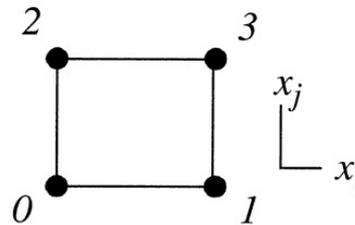
(e) Triangle



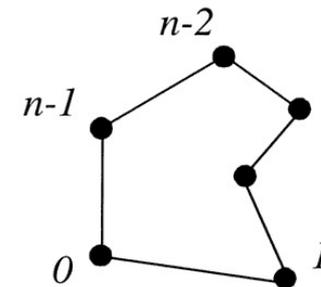
(f) Triangle strip (n triangles)



(g) Quadrilateral

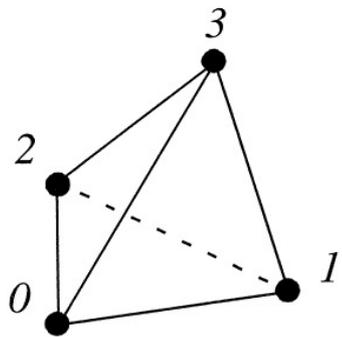


(h) Pixel

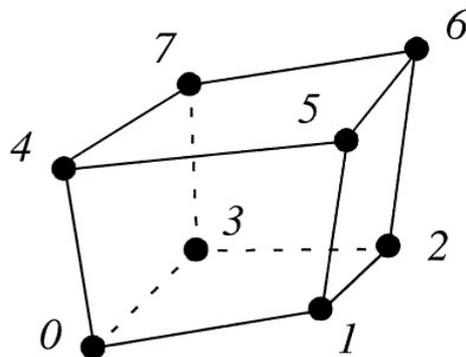


(i) Polygon (n points)

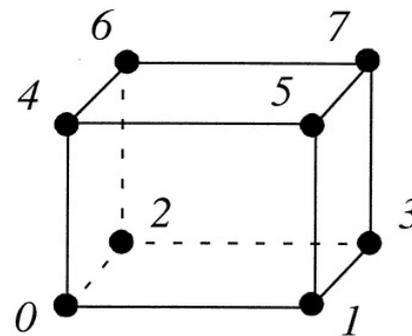
- Cell topology defined by **connectivity** of vertices



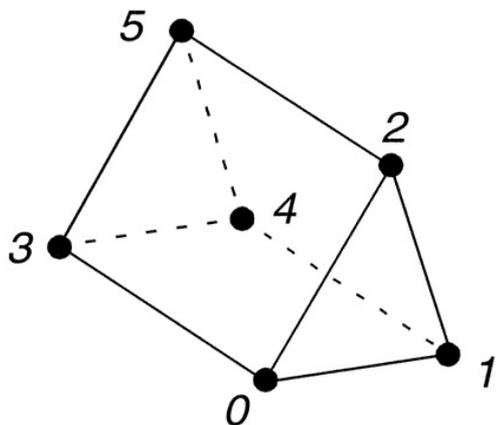
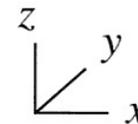
(j) Tetrahedron



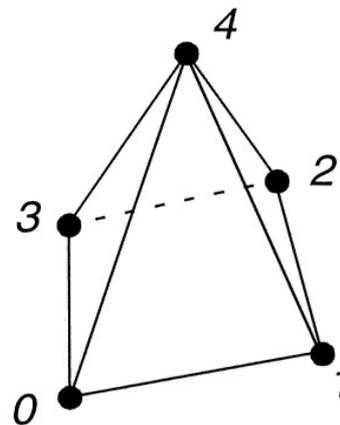
(k) Hexahedron



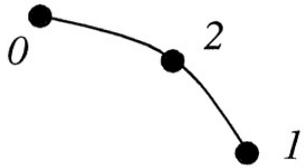
(l) Voxel



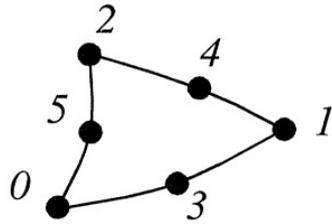
(m) Wedge



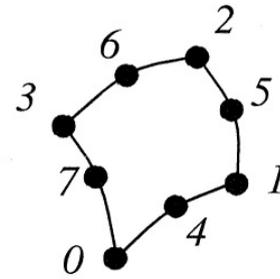
(n) Pyramid



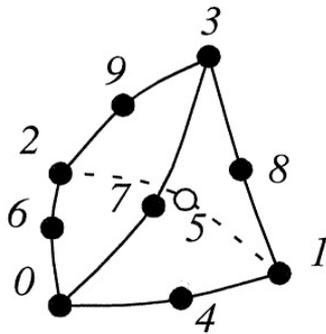
(a) Quadratic Edge



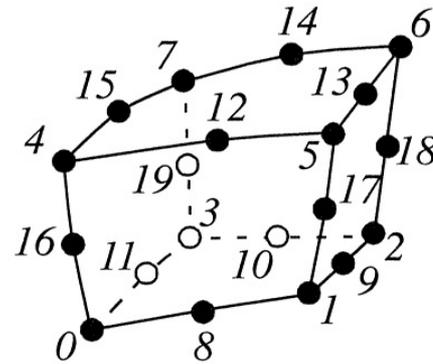
(b) Quadratic Triangle



(c) Quadratic Quadrilateral



(d) Quadratic Tetrahedron

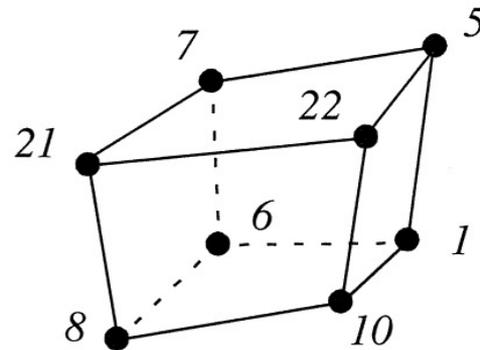


(e) Quadratic Hexahedron

Cell Example: Hexahedron

- Vertices listed in special order define topology

Definition:
Type: hexahedron
Connectivity: (8,10,1,6,21,22,5,7)



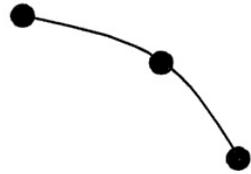
Point list

$x-y-z$
$x-y-z$
\vdots
$x-y-z$
$x-y-z$

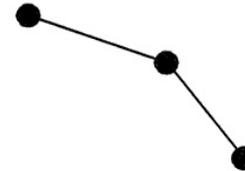
Non-Linear Cell Decomposition

- Non-linear cells must be linearized for visualization
- Break non-linear cells into linear cells

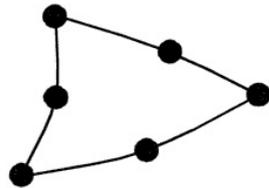
Non-Linear Cell Decomposition



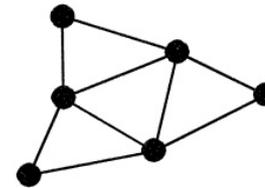
Quadratic Edge



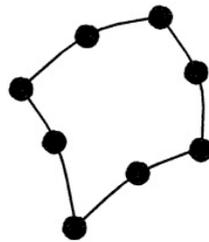
Two lines



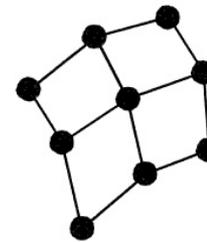
Quadratic Triangle



Four triangles



Quadratic Quadrilateral



Four quadrilaterals

Attribute Data

- Data values (attributes) usually assigned to vertices, as opposed to edges or faces
- Why?
- Interpolation concept easy to apply across edges and faces
- Common attributes include:
 - Temperature, density, velocity, pressure, heat flux, chemical concentration, others
- Scalars, vectors, tensors

Attribute Data

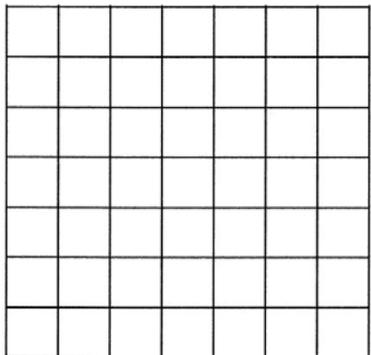
- **Scalar** data is data that is single-valued at all locations in a data-set
- Examples: temperature, stock price, elevation
- **Vector** data is data with magnitude and direction
- Examples: position, velocity, acceleration
- **Normals** (direction vectors) are vectors of magnitude 1
- **Texture coordinates** map a point from Cartesian space into a 1-D, 2-D or 3-D texture space
- Textures let us add color, transparency and other details to geometric shapes

Attribute Data

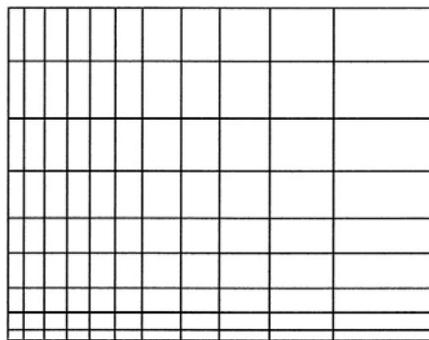
- **Tensors** are mathematical generalizations of vectors and scalars
- Usually written as matrices
- Tensor visualization is extremely difficult

Types of Data-sets

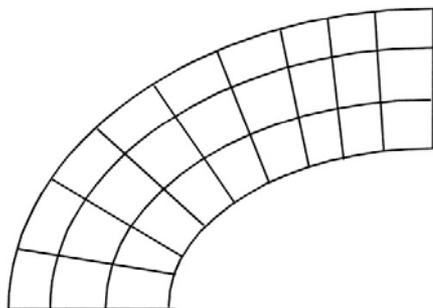
- Regular vs. irregular structure – refers to topology of data-set
- Data-sets with regular topology, we do not need to store connectivity information
- Points themselves can be regular or irregular
- If irregular, we need to store the positions
- Unstructured data must be explicitly represented
- High computational and storage costs usually



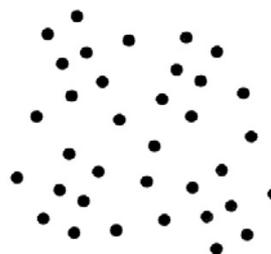
(a) Image Data



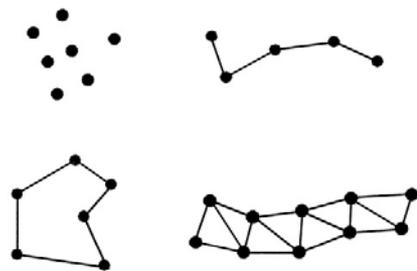
(b) Rectilinear Grid



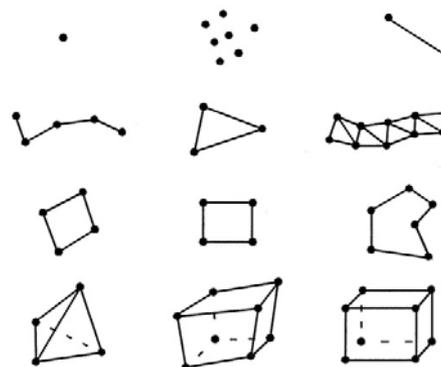
(c) Structured Grid



(d) Unstructured Points



(e) Polygonal Data



(f) Unstructured Grid

Polygonal Data

- Vertices, edges, polygons, polylines, triangle strips, etc.
- Triangle strips can represent n triangles using only $n+2$ points, vs. $3n$ points normally required

Image Data

- Collection of points and cells on a regular, rectangular grid
- Also called a “raster”
- (Book uses word “lattice” – avoid!)
- 2D grid  image
- 3D grid  volume
- i - j - k coordinate system parallel to global x - y - z coordinate system
- Simple representation, but “curse of dimensionality”

Rectilinear Grid

- Regular grid, but spacing along axes can vary
- Need to store 3 extra arrays of length n_x , n_y , n_z – dimensions of the grid
- Each array stores spacing, basically

Structured Grid

- Regular topology, irregular geometry
- Curvilinear grids most common type

Unstructured Points

- No topology, irregular geometry
- Also called **point clouds**

Unstructured Grid

- Irregular topology and geometry
- Any combination of cells permitted
- Encountered in relatively few applications
- e.g., computational geometry

Fundamental Visualization Algorithms

Visualization Algorithms

- “Algorithms that transform data are the heart of visualization”
- Algorithms classified according to **structure** and **type** of data
- **Geometric transformations** change geometry but not topology
- Examples: translation, rotation, scaling
- **Topological transformations** change topology but not geometry
- Example: convert from regular to irregular grid

Visualization Algorithms

- **Attribute transformations** convert or create attributes in data
- Example: convert vector to scalar
- **Combined transformations** change data structure and attributes
- Algorithms that change data type include **scalar algorithms, vector algorithms, tensor algorithms, and modeling algorithms**
- **Volume visualization** and **vector visualization** have their own special algorithms

Scalar Algorithms

- **Color mapping** – map scalar data to colors
- Why scalars?
- How would you map a vector to a color?
- **Color lookup table (LUT)** – attributes inside particular range are mapped to color

$$s_i < \min, i = 0$$

$$s_i > \max, i = n - 1$$

$$i = n \left(\frac{s_i - \min}{\max - \min} \right)$$

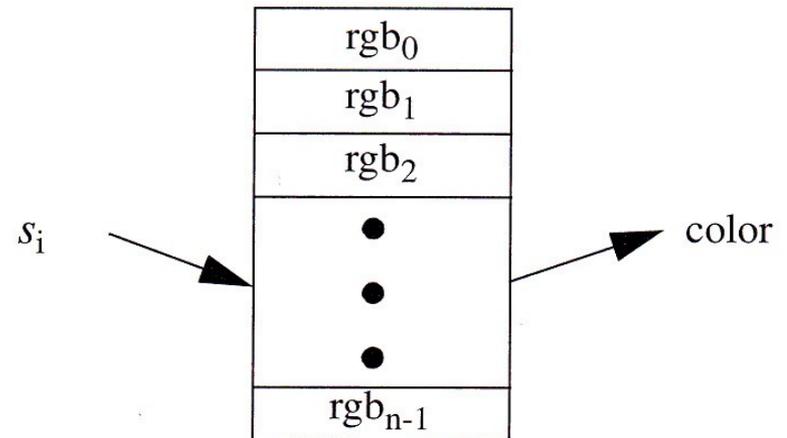


Figure 6–1 Mapping scalars to colors via a lookup table.

Transfer Functions

- More general form of lookup table
- Can map data to color as well as transparency
- Usually expressed as actual functions

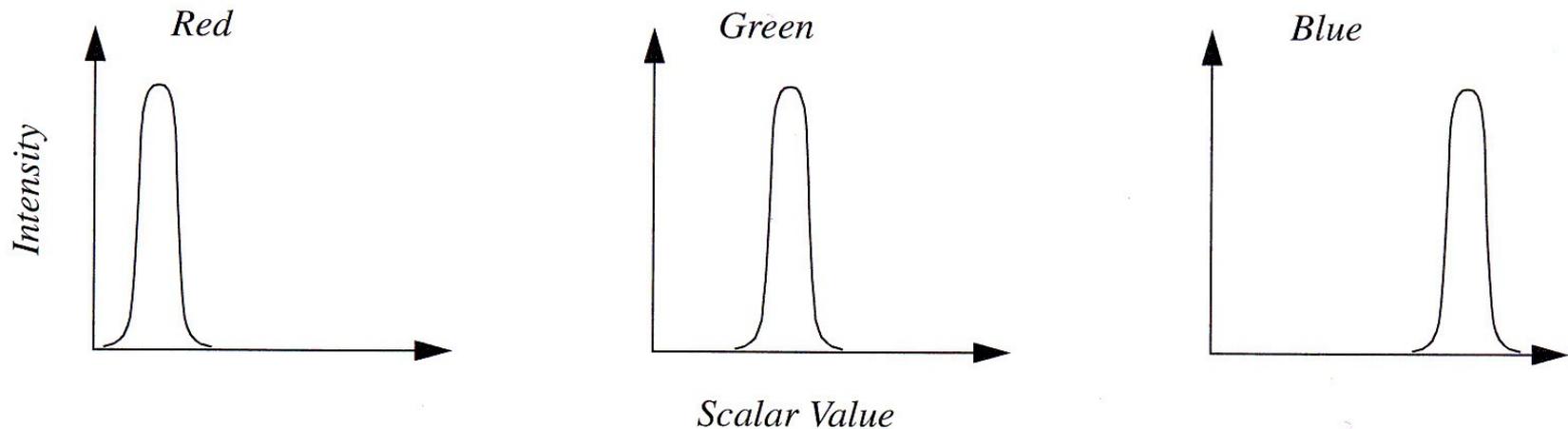
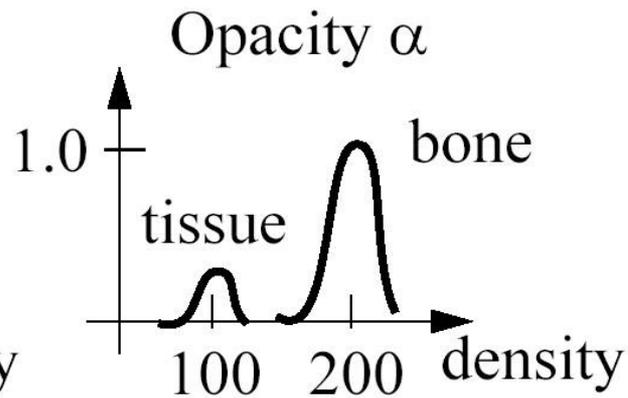
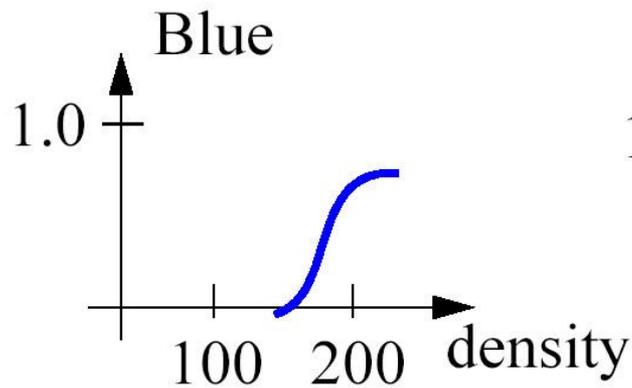
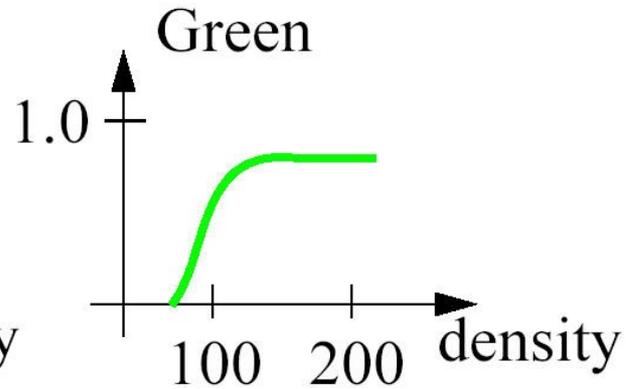
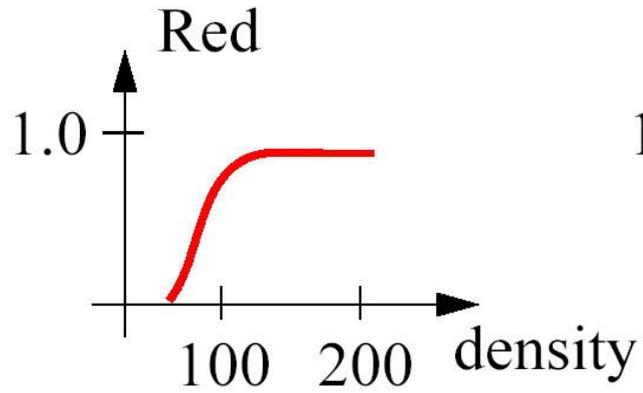


Figure 6–2 Transfer function for color components red, green, and blue as a function of scalar value.

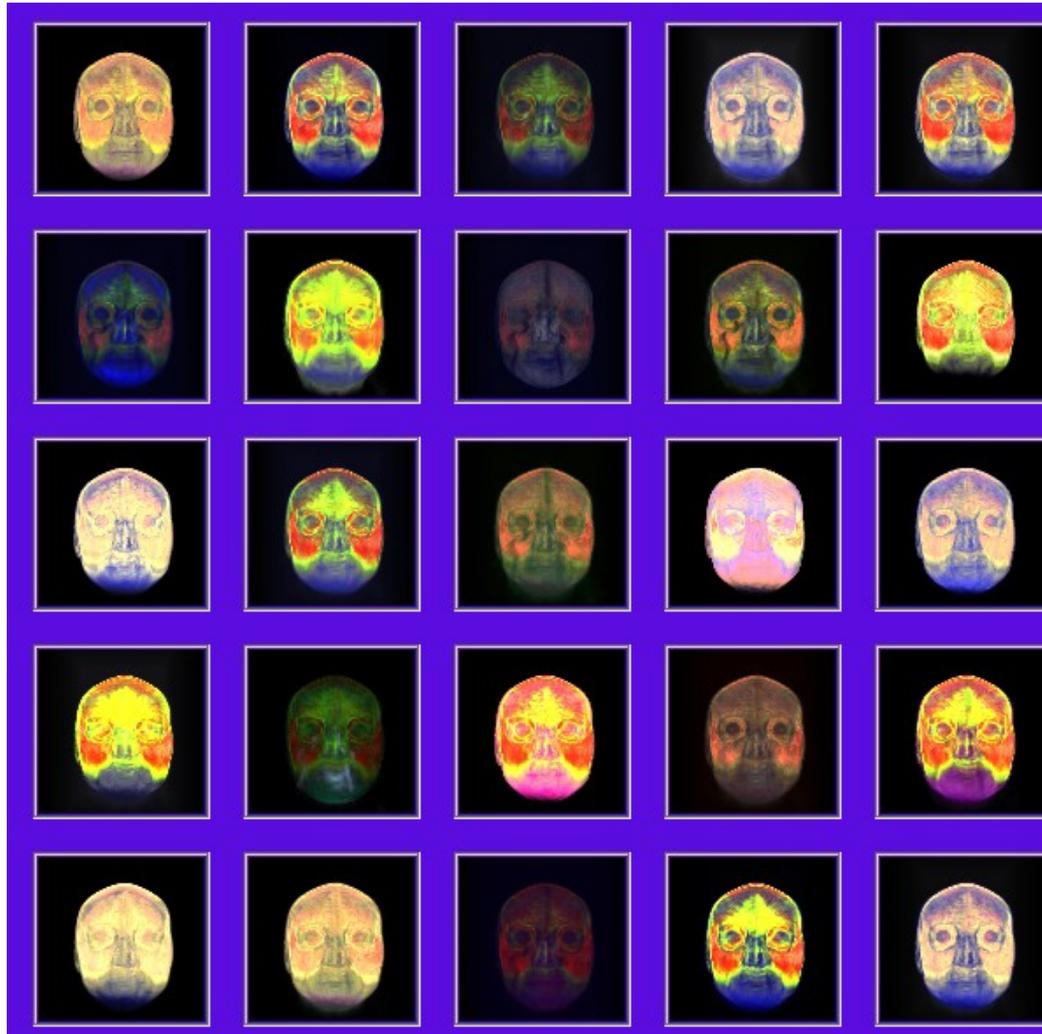
Transfer Functions



Transfer Functions

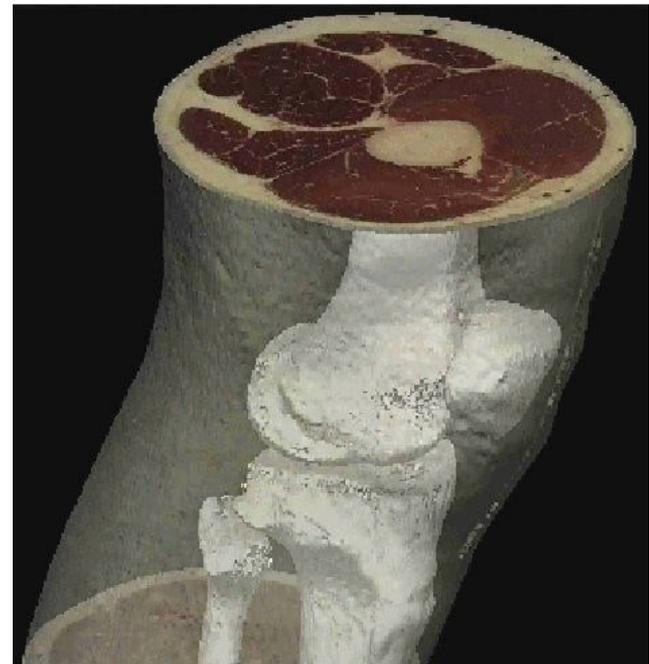
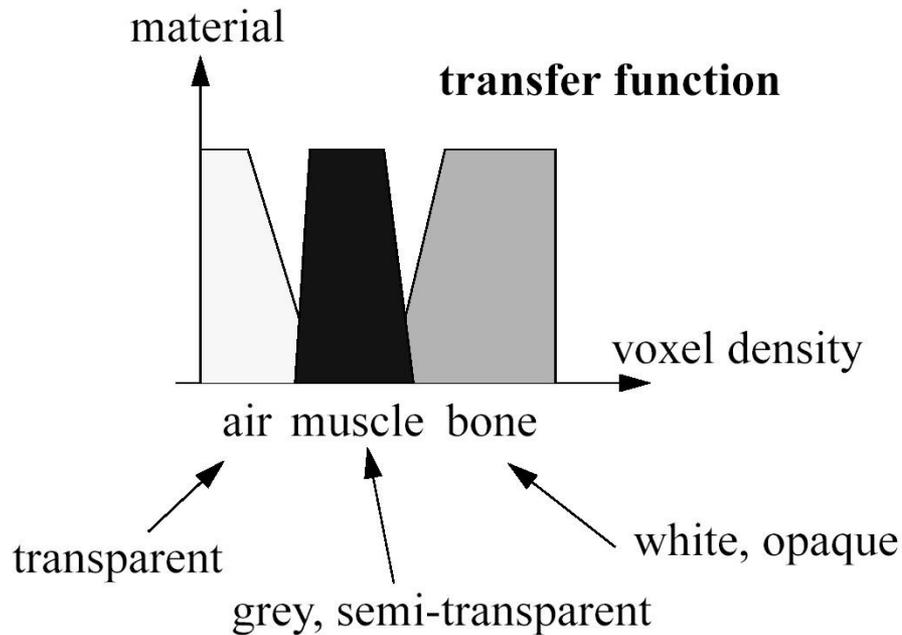
- Difficult to design
- Semi-automatic systems exist: **transfer function design galleries**
- Idea: generate random transfer functions, user selects ones he likes, system *mutates* them using a genetic algorithm to create new ones

Transfer Function Design Galleries



Transfer Functions

- The assignment of color and transparency to density is also called **classification**



Transfer Functions

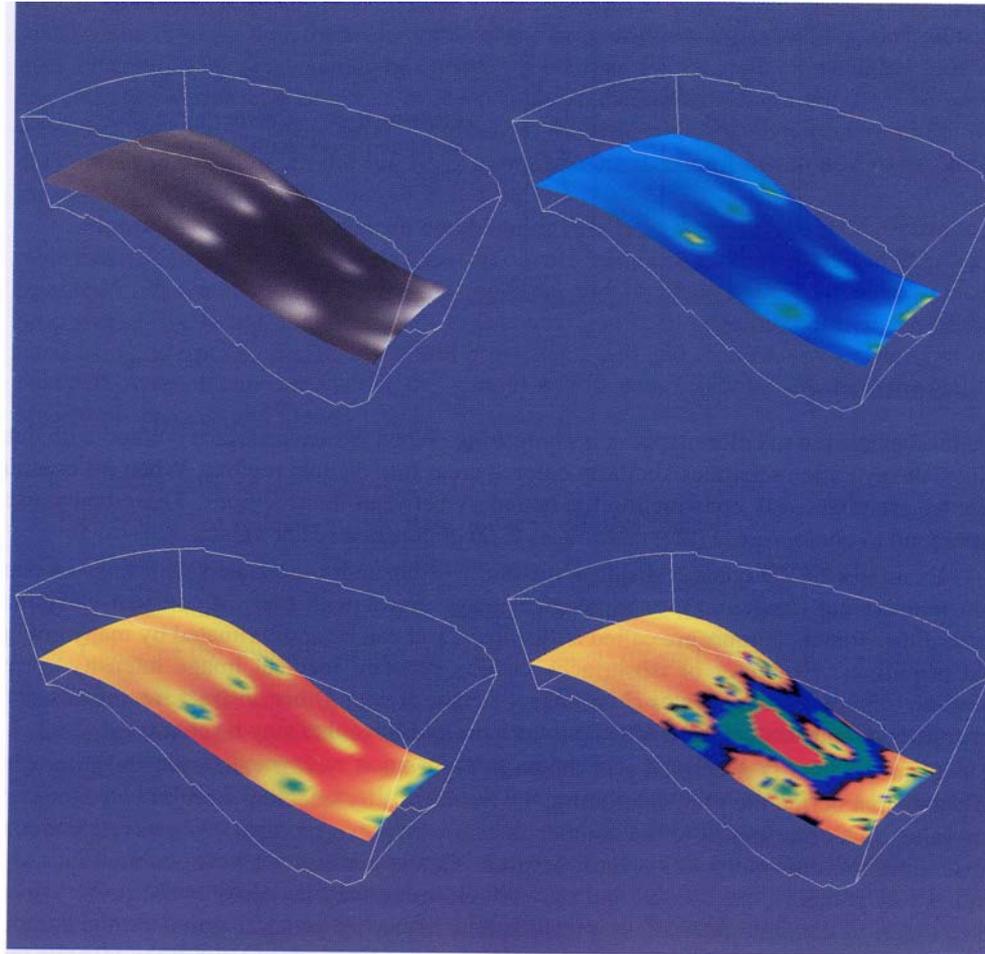


Figure 6-3 Flow density colored with different lookup tables. Top-left: grayscale; Top-right rainbow (blue to red); lower-left rainbow (red to blue); lower-right large contrast (`rainbow.tcl`).

Contouring

- **Isocontour** and **isosurface extraction** can reveal structure of data (e.g., isobars on weather maps)
- Separate data into regions
- Isocontours: connected line segments
- Isosurfaces: triangular meshes

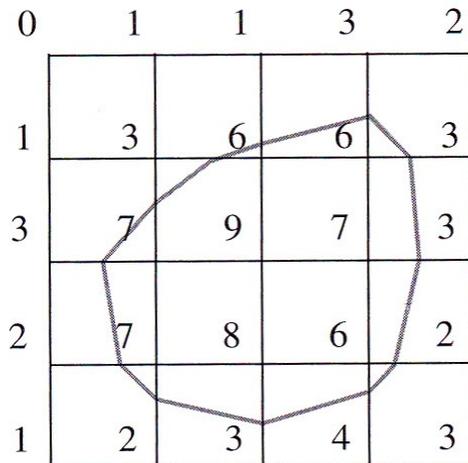


Figure 6-4 Contouring a 2D structured grid with contour line value = 5.

Contouring

- Isolines cross cell boundaries
- Use **interpolation** to compute crossing point
- **Marching squares** algorithm processes each quadrilateral cell independently
- Each vertex may be inside or outside (or on) contour
- How many cases must we consider?
- Ambiguous cases

Marching Squares Cases

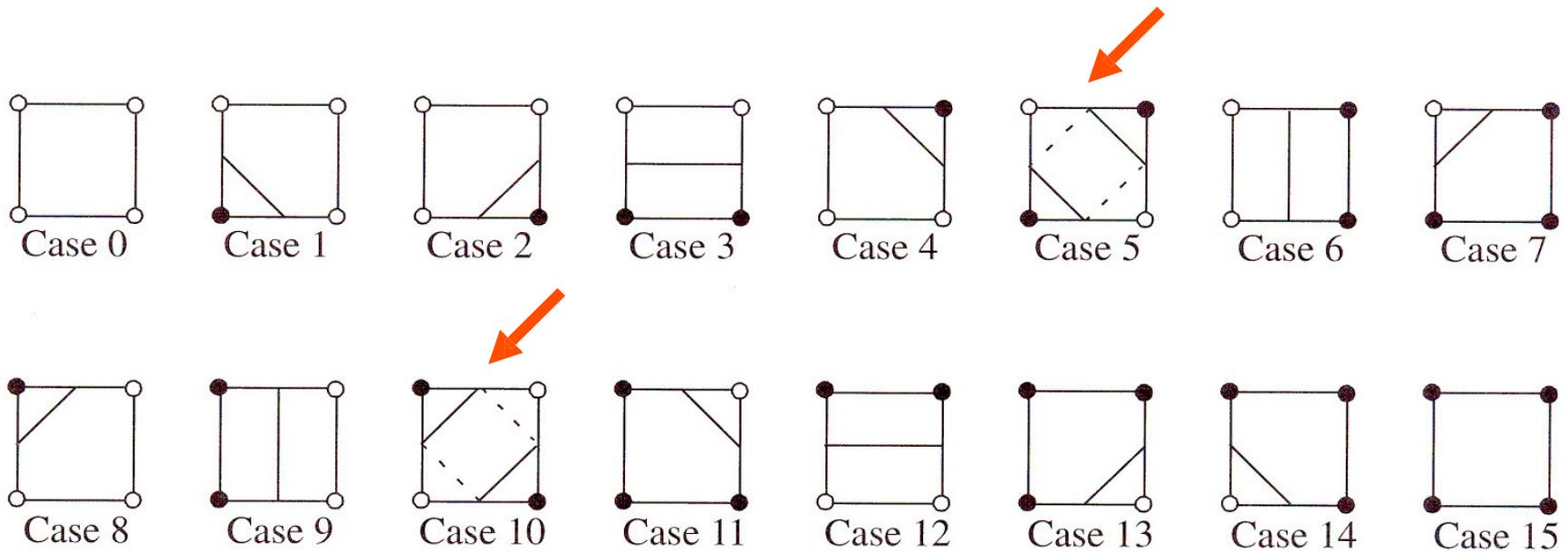


Figure 6–5 Sixteen different marching squares cases. Dark vertices indicate scalar value is above contour value. Cases 5 and 10 are ambiguous.

Marching Squares Ambiguous Case

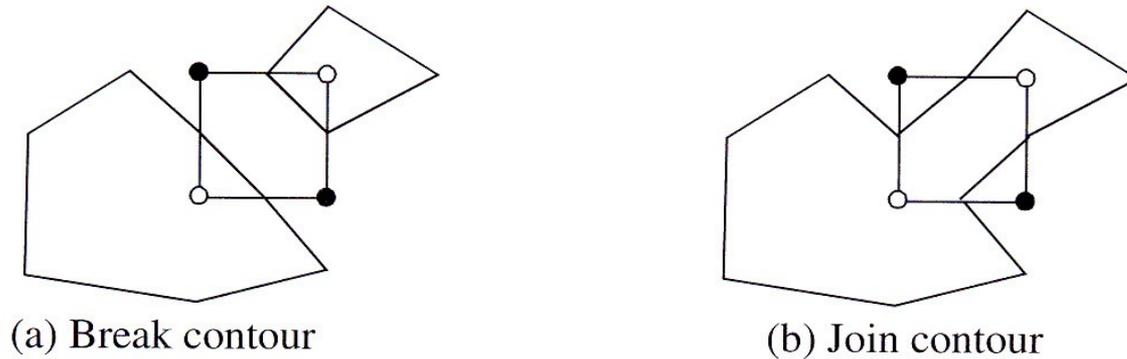


Figure 6–8 Choosing a particular contour case will break (a) or join (b) the current contour. Case shown is marching squares case 10.

Marching Cubes

- **Marching cubes** algorithm extracts isosurfaces from 3D rasters
- Very famous algorithm
- How many cases of hexahedral cells must we consider?
- Each of 8 vertices may be inside or outside
- $2^8 = 256$
- Lots of symmetry  really only 15 cases to consider

Marching Cubes

Cases

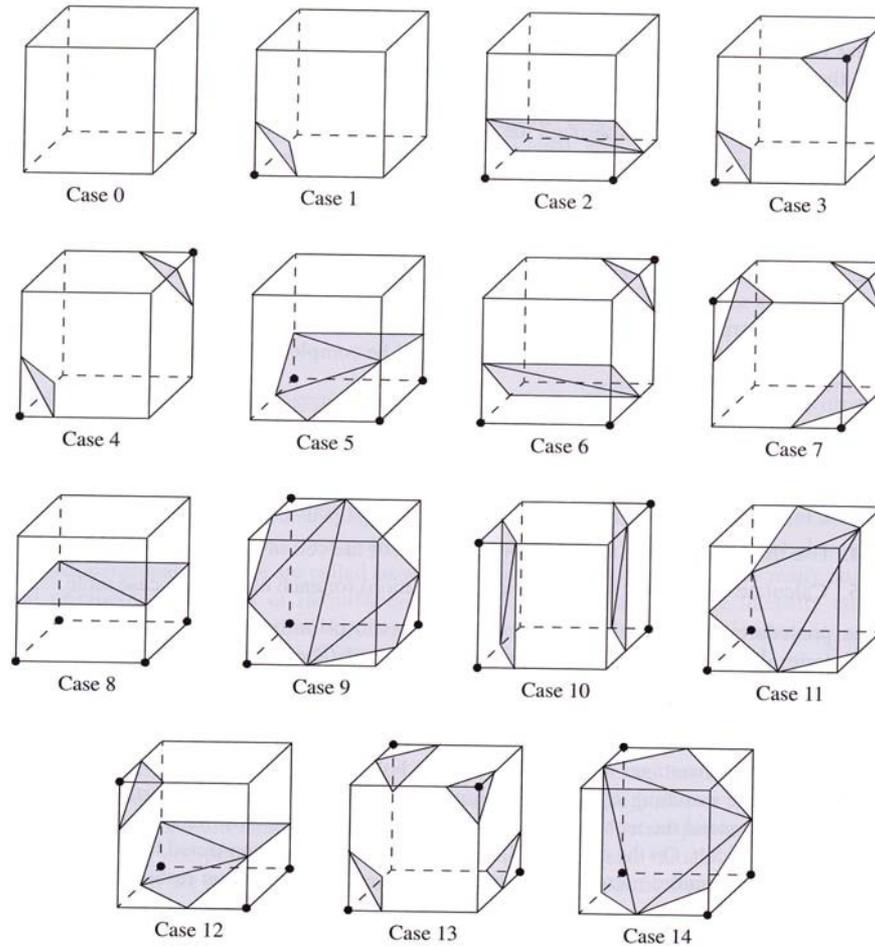
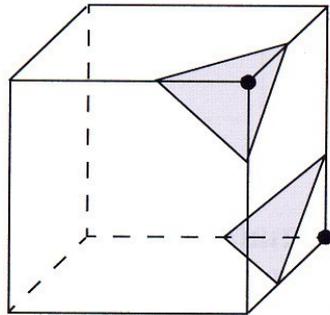
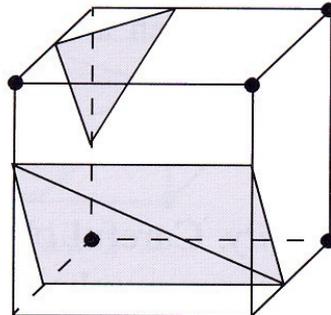


Figure 6-6 Marching cubes cases for 3D isosurface generation. The 256 possible cases have been reduced to 15 cases using symmetry. Dark vertices are greater than the selected isosurface value.

Marching Cubes Ambiguous Cases



Case 3



Case 6c

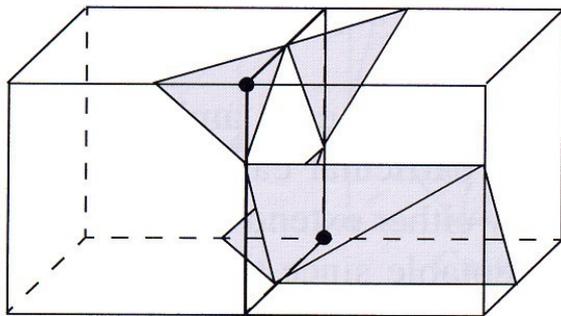
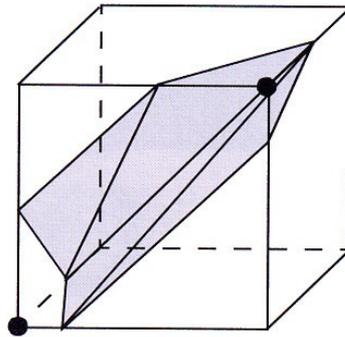
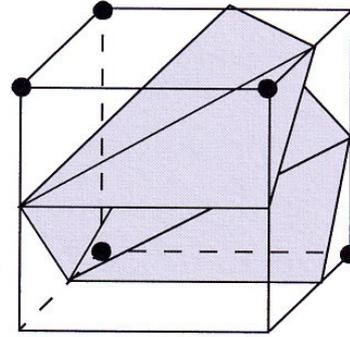


Figure 6–9 Arbitrarily choosing marching cubes cases leads to holes in the isosurface.

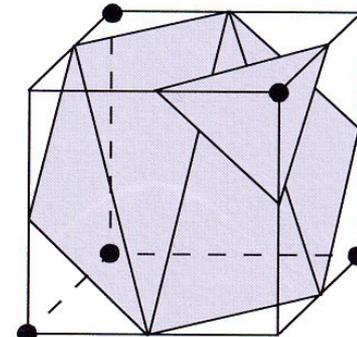
Marching Cubes Complementary Cases Used to Avoid Holes



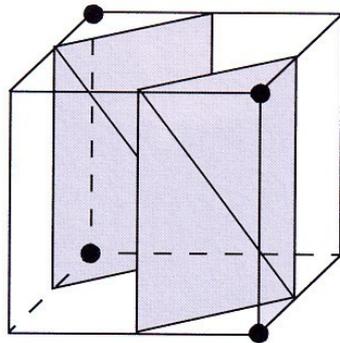
Case 3c



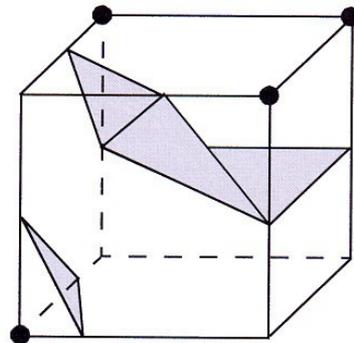
Case 6c



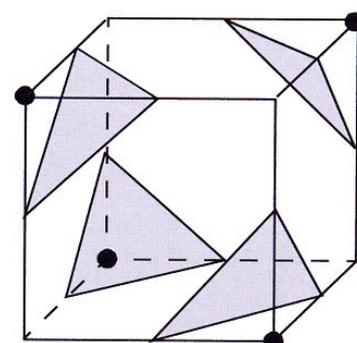
Case 7c



Case 10c



Case 12c



Case 13c

Figure 6–10 Marching cubes complementary cases.

Marching Triangles & Tetrahedra

- Can extend/simplify marching squares to *marching triangles*, and marching cubes to *marching tetrahedra*
- Divide squares into triangles, cubes into tetrahedra (how?) and then run different algorithms
- Tradeoff for both algorithms: simplicity vs. memory usage

Contouring Examples

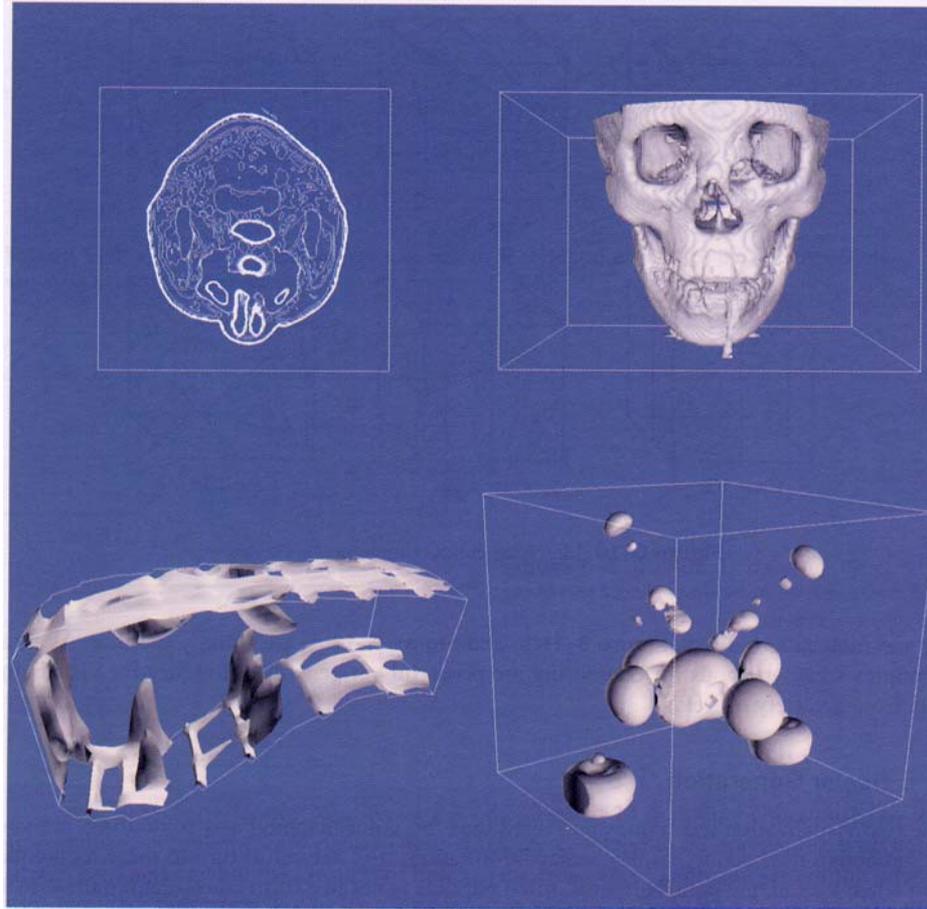


Figure 6-11 Contouring examples. (a) Marching squares used to generate contour lines (`headSlic.tcl`); (b) Marching cubes surface of human bone (`headBone.tcl`); (c) Marching cubes surface of flow density (`combIso.tcl`); (d) Marching cubes surface of iron-protein (`ironPIso.tcl`).

Scalar Generation

- Vectors and other n-D quantities can be turned into scalars
- Example: taking magnitude of vector
- Example: Hawaii terrain visualization created by projecting vector onto vertical
- Normalize vectors to give maximum magnitude of 1.0
- Steepest slope mapped to brightest color

Scalar Generation

$$s_i = \frac{(p_i - p_l) \cdot (p_h - p_l)}{|p_h - p_l|^2}$$

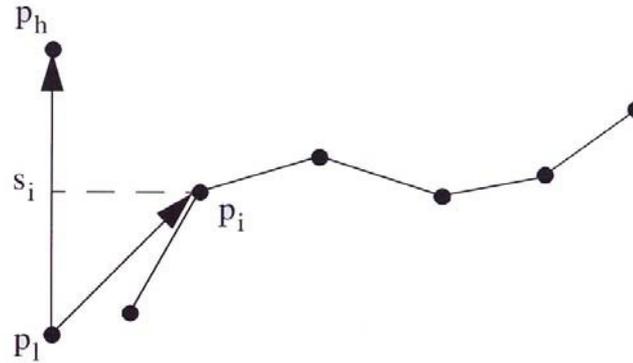
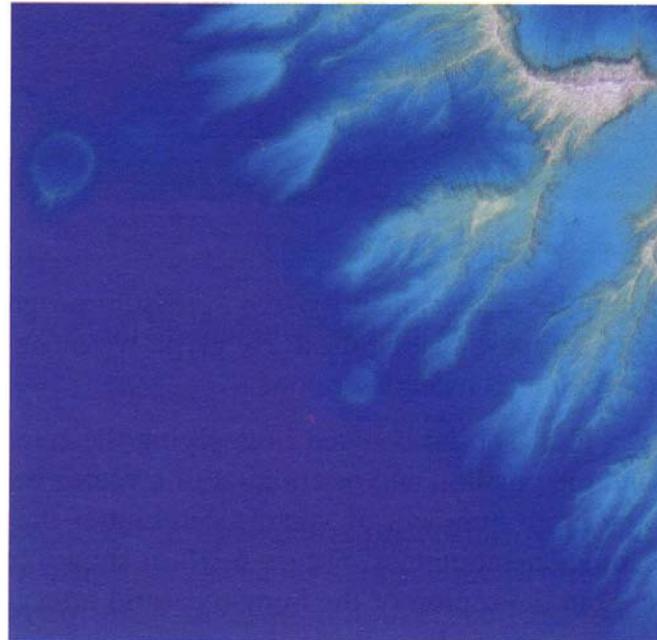


Figure 6-12 Computing scalars using normalized dot product. Bottom half of figure illustrates technique applied to terrain data from Honolulu, Hawaii (`hawaii.tcl`).

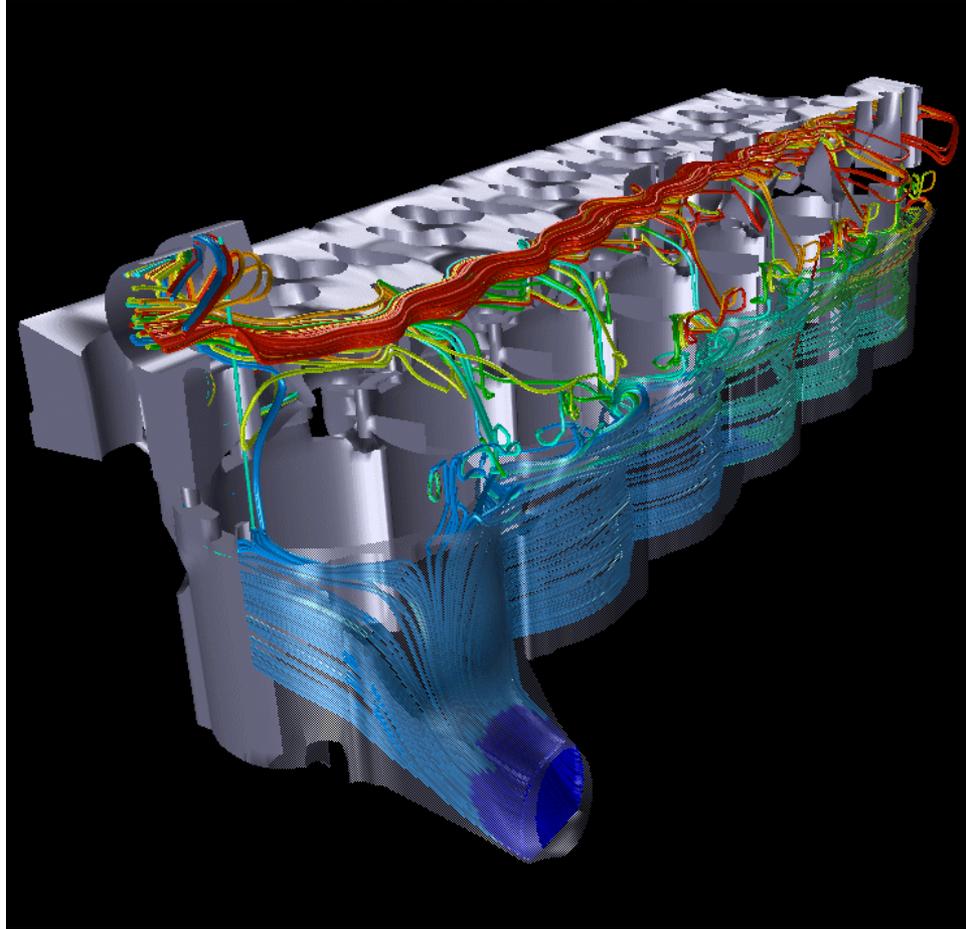


Vector Field Visualization

- Streamlines
 - Integration through vector field
- Stream ribbons
 - Connect two streamlines
- Streamtubes
 - Connect three or more streamlines
- Stream surfaces
 - Sweep line segment through vector field

Streamlines

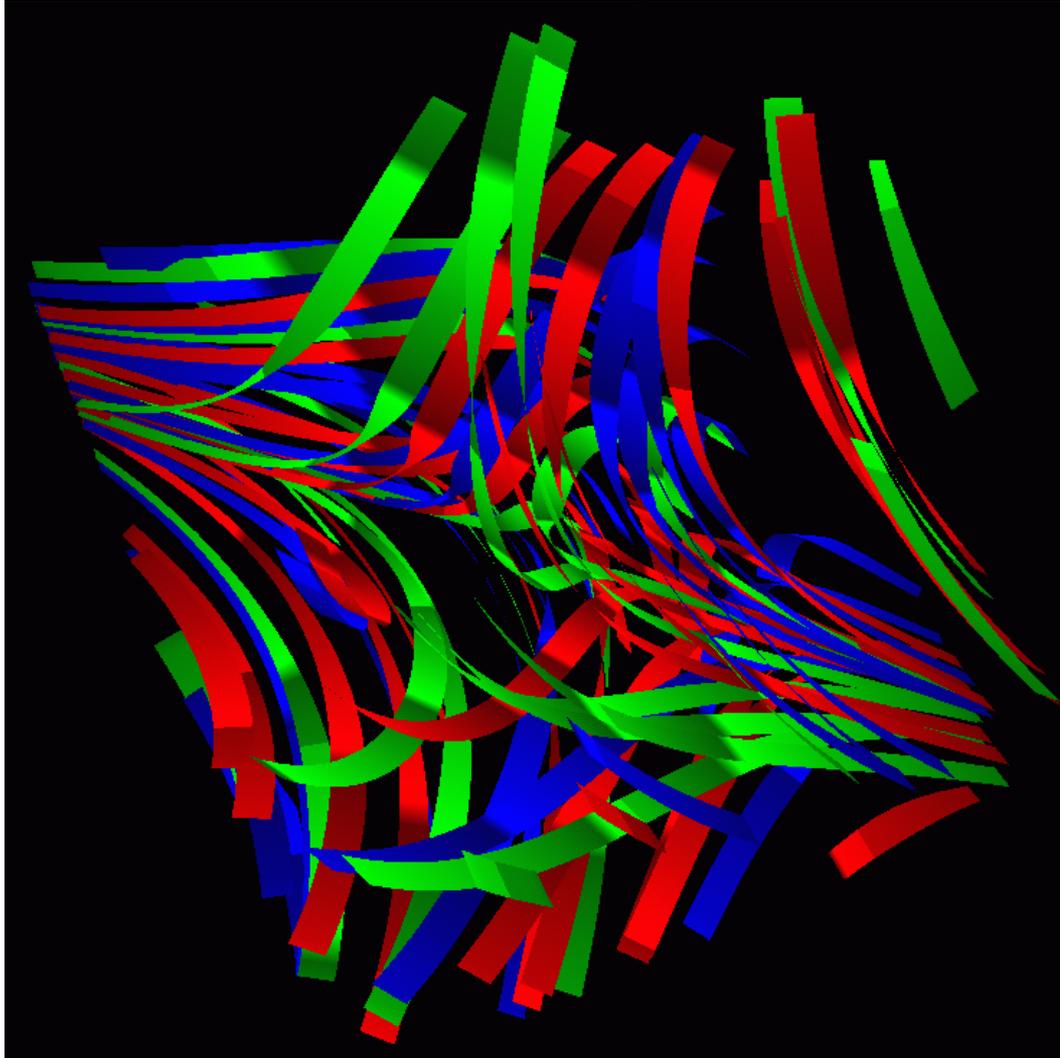
Example



Color indicates temperature of air flowing through engine

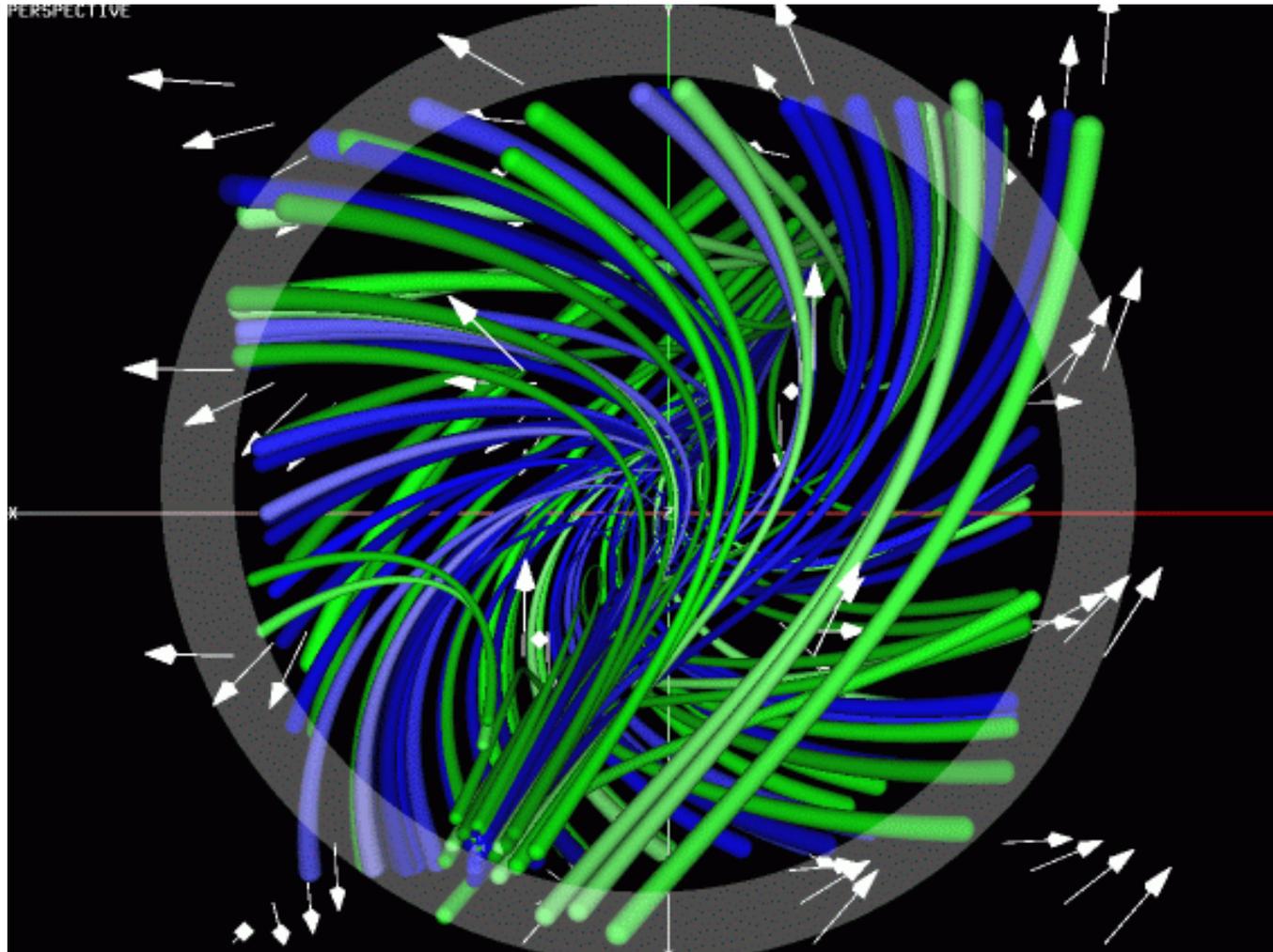
Streamribbons

Example



Streamtubes

Example



Streamsurfaces

Example

